

# Algorithmic Developments and Software Engineering for Scalable Sparse Eigensolvers in the DFG Project ESSEX

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project ESSEX



Knowledge for Tomorrow



## Survey

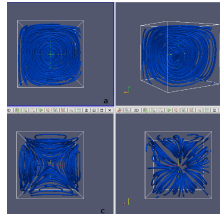
- Use Case: Linear Stability Analysis
- Block Jacobi-Davidson Eigensolver with Preconditioning
- BEAST Framework
- Chebyshev Filter Diagonalization
- Programming Model
- Solver Toolkit **PHIST**
- Outlook



## Use Case: Linear Stability Analysis of 3D Flow Problems

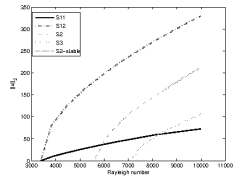
### Problem setting

- incompressible Navier-Stokes
- Boussinesq approximation
- structured C-grid ('staggered grid')
- linear stability analysis: compute most unstable eigenmodes of the Jacobian  $A$ .



### Numerical challenge

- solve  $Ax = \lambda Bx$  for the right-most eigenpairs  $(\lambda, x)$ ,
- $A$  is large, sparse and non-symmetric,
- $A$  is a *saddle point matrix*,
- $B$  is symmetric and positive semi-definite.



## Block Jacobi-Davidson Eigensolver in PHIST

### Block JDQR algorithm

- extend basis  $V$  by  $k$  vectors per iteration
- Rayleigh-Ritz, solve  $V^T A V \tilde{s} = \tilde{\lambda} V^T B V \tilde{s}$
- correction equation: solve  $(A - \tilde{\lambda} B)t = -\text{res}, t \perp_B V$

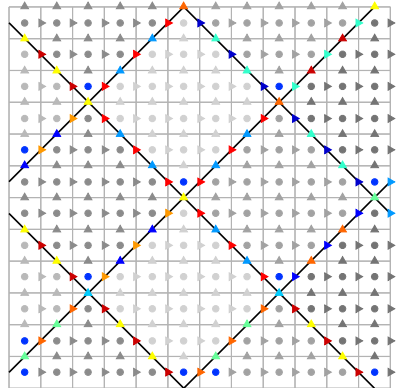
### Performance gain over single-vector algorithm:

- better cache performance of SpMVM
- fewer synchronizations by collecting dot products
- blocked and fused kernels to additionally save memory traffic



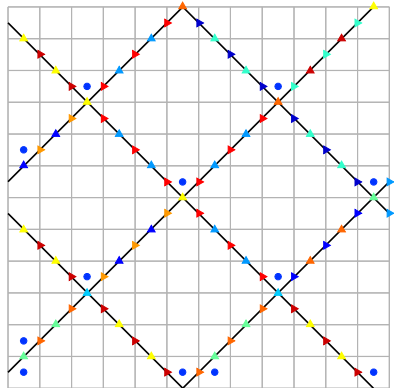
## SMILU: Staggered-Grid Multi-Level ILU

- Partition into **many** small subdomains



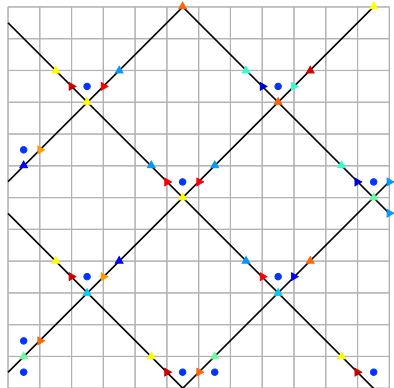
## SMILU: Staggered-Grid Multi-Level ILU

- Partition into **many** small subdomains
- eliminate interior



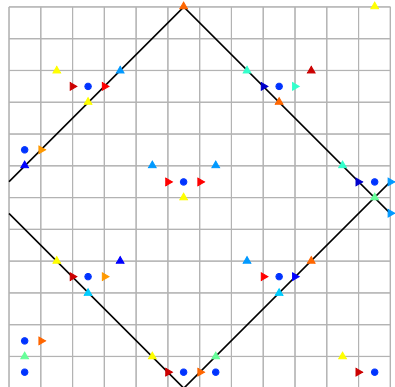
## SMILU: Staggered-Grid Multi-Level ILU

- Partition into **many** small subdomains
- eliminate interior
- aggregate and drop on separators



## SMILU: Staggered-Grid Multi-Level ILU

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- aggregate and drop on separators
- repeat recursively

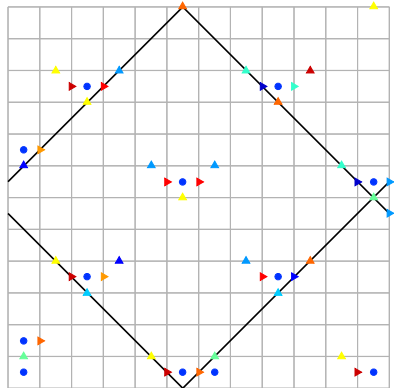




## SMILU: Staggered-Grid Multi-Level ILU

- Partition into **many** small subdomains
- eliminate interior
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- repeat recursively

⇒ Robust, spectrally equivalent,  
mass and energy conserving ILU



## Solving the JD Correction Equations

Let  $V = [V_1, V_2]^T$ ,  $W = BV$ . A **bordered Schur-Complement preconditioner**

$$\begin{pmatrix} A_{11} & A_{12} & W_1 \\ A_{21} & A_{22} & W_2 \\ V_1^T & V_2^T & 0 \end{pmatrix} \approx \begin{pmatrix} L_{11} & 0 & 0 \\ A_{21}U_{11}^{-1} & \hat{L}_{22} & \\ \hat{V}_1^T & & \end{pmatrix} \begin{pmatrix} U_{11} & L_{11}^{-1}A_{12} & \hat{W}_1 \\ 0 & \hat{U}_{22} & \\ 0 & & \end{pmatrix}$$

where

$$\hat{L}_{22}\hat{U}_{22} \approx \begin{pmatrix} A_{22} - A_{21}A_{11}^{-1}A_{12} & W_2 - A_{21}\hat{W}_1 \\ V_2^T - \hat{V}_1^T A_{12} & -\hat{V}_1^T \hat{W}_1 \end{pmatrix}, \hat{W}_1 = L_{11}^{-1}W_1, \hat{V}_1^T = V_1^T U_{11}^{-1}.$$

- yields vectors (B-)orthogonal to the search space  $V$ ,
- only needs to re-factor last-level Schur complement when updating  $V$ ,
- does not increase the fill because  $V$  is already dense.



## BEAST (Beyond FEAST)



FEAST

Polizzi, 2009



BEAST

(Beyond fEAST)

An implementation of the FEAST algorithm, Chebyshev filter diagonalization, and, most recently, CIRR/SSM to solve large scale eigenproblems  $AX = BX\Lambda$  (with  $A = A^H$ ,  $B$  hpd) in an interval  $[\underline{\lambda}, \overline{\lambda}]$  on hybrid-parallel high performance supercomputers.



## BEAST Framework

Choose  $Y \in \mathbb{C}^{n \times m}$

### Possible projections:

- $U = S(A)Y$ , where  $S(\lambda) = \sum_{i=0}^d c_i T_i(\lambda)$  (Polynomial)
- $U \approx \frac{1}{2\pi i} \oint_C (zB - A)^{-1} BY dz$  (FEAST)
- $U = [U^0, U^1, \dots, U^{l-1}]$  with  $U^k = \frac{1}{2\pi i} \int_C z^k (zB - A)^{-1} BY dz$  (SSM)

Postprocess  $U$

Rayleigh-Ritz:  $\begin{cases} A_U := U^H A U; & B_U := U^H B U; \\ \text{Solve } A_U W = B_U W \Lambda; & X := U W \end{cases}$

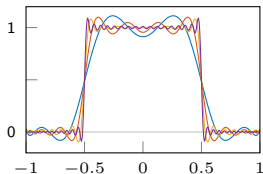
Repeat with  $Y := X$



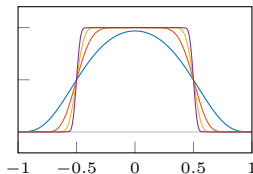
## Traditional Polynomial Filters

$$S(\lambda) = \sum_{i=0}^d c_i T_i(\lambda)$$

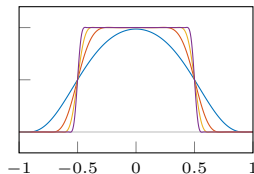
Dirichlet



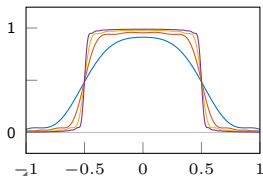
Jackson



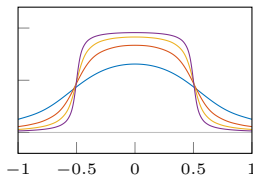
Lanczos(1)



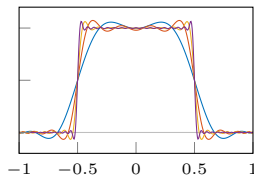
Fejer



Lorentz(1)



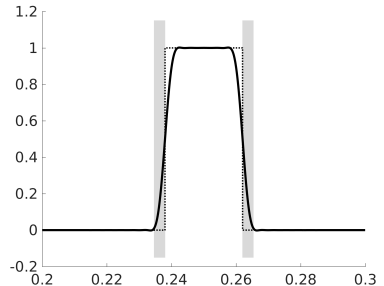
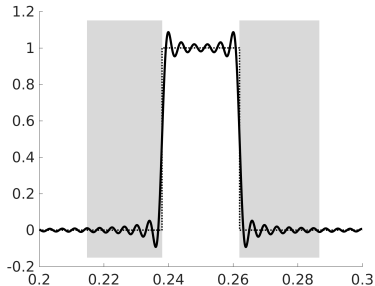
Wang-Zunger(1,1)



## A-Priori Optimization of Separation Properties

Require

- $S(\lambda) \geq \tau_{\text{inside}}$  for  $\lambda \in [\underline{\lambda}, \bar{\lambda}]$
- $|S(\lambda)| \leq \tau_{\text{outside}}$  for  $\lambda \notin [\underline{\lambda} - \delta, \bar{\lambda} + \delta]$



Goal: minimize  $\delta$ ; adaptively control the polynomial degree



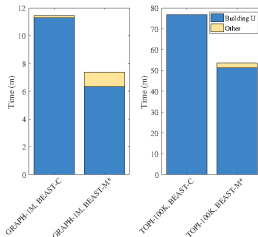
## Using BEAST with Moments

Use Sakurai-Sugiura methods (SS-RR) to reduce cost of building  $U$

$$U_j^0 = (z_j B - A)^{-1} B Y$$

The diagram illustrates the construction of  $U_j^0$  as a sum of moments. It shows a sequence of terms:  $U_j^0$ , followed by an ellipsis, then  $z_j^{l-1} U_j^0$ , and finally  $z U_j^0$ . The terms are represented by vertical bars of increasing height, with the last term being the tallest. The entire sequence is enclosed in a dashed box.

- $U$  constructed using moments  $(z_j^k)$
- Reduce overall number of right hands sides



- Improvement compared to pure FEAST scheme
- BEAST-M\*: switch from SS-RR to FEAST between iterations



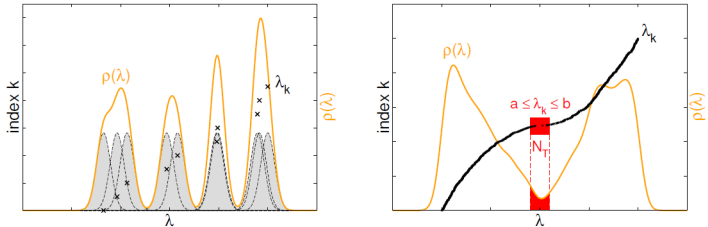
## BEAST Framework Features

- Leverage the hybrid-parallel performance of **GHOST**
- A priori eigencount estimation via KPM (soon also stochastic estimation)
- Locking of converged eigenpairs (w/ re-orthogonalization)
- On-the-fly eigencount estimation and subspace reduction
- Generic linear solver interface, CARP-CG (via **PHIST** )
- Adaptive choice of polynomial degree (and number of integration nodes)
- Optimized polynomial coefficients
- SDC detection (also Checkpointing, in the future)
- Mixed precision
- Multi-level parallelism
- Orthogonality





## ChebFD: Chebyshev Filter Diagonalization



(large sparse) symmetric / Hermitian matrix  $A$

interior eigenvalues  $\lambda_k, \lambda_{k+1}, \dots, \lambda_{k+N_T} \in [a, b]$

# target values

eigenvalue density (density of states)  $\rho(\lambda) = \sum_k \underbrace{\delta(\lambda - \lambda_k)}_{\text{smoothed}}$

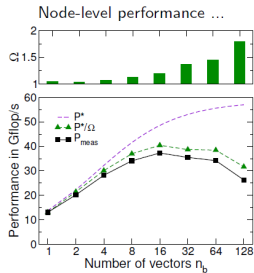
$$N_T \approx \int_a^b \rho(\lambda) d\lambda$$

A. Pieper, M. Kreutzer, A. Alvermann, M. Galgon, H. Fehske, G. Hager, B. Lang, G. Wellein,  
 "High-performance implementation of Chebyshev filter diagonalization for interior eigenvalue computations",  
*J. Comp. Phys.* 325, 226 (2016).



## ChebFD: Parallel Implementation

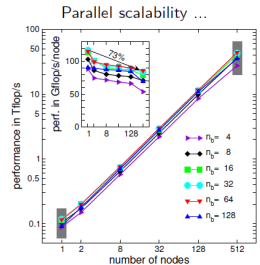
- ▶ uses only spMVM  $\Rightarrow$  suitable for very large unstructured matrices
- ▶ convergence depends on eigenvalue density  $\Rightarrow$  large number of spMVMs required
- ▶ search vectors  $\gg$  target vectors  $\Rightarrow$  massive block algorithm  $\Rightarrow$  spMMVM



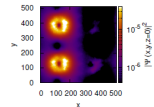
... is high with spMMVM

- ▶ matrix dimension  $\approx 10^9$  no problem even for  $\approx 200$  interior eigenvalues

Matrix	Nodes	$D$	$[\lambda : \lambda]_{int}$	$N_I$	$N_p$	Runtime [hours]	Sust. perf. [Tflop/s]
topi1	32	6.71e7	7.27e-3	148	2159	3.2 (83%)	2.96
topi2	128	3.64e-3	1.82e-3	148	4319	4.9 (88%)	11.5
<b>topi3</b>	<b>512</b>	<b>1.07e9</b>	<b>4.84e-4</b>	104	32463	10.1 (90%)	<b>43.9</b>
graphene1	128	4.84e-4	2.42e-4	104	64926	10.8 (98%)	4.6
graphene2	512	1.07e9	2.42e-4	104	64926	16.4 (99%)	18.2



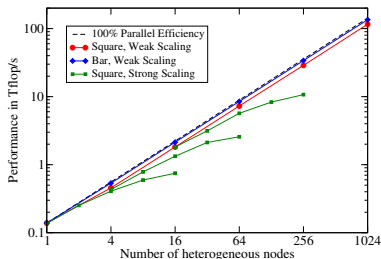
... is good due to iterative scheme (e.g., few synchronization points)



## SPMD/OK Programming Model

- SPMD ('BSP') vs. task parallelism
- Heterogenous cluster: distribute problem according to limiting resource (e.g. memory bandwidth)
- **Optimized Kernels** make sure each component runs as fast as possible
- User sees a simple functional interface (no general-purpose looping constructs etc.)

**A success story:** Chebyshev methods on Piz Daint



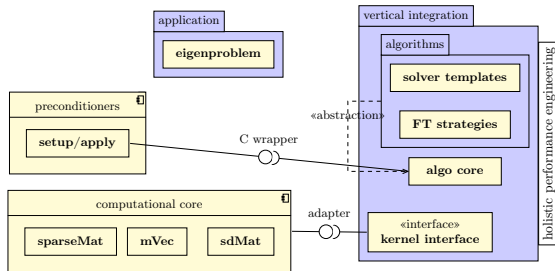
Only needs sparse matrix times multiple vector (spMMV) products and an occasional vector operation



## PHIST Software Architecture

### a Pipelined Hybrid-parallel Iterative Solver Toolkit

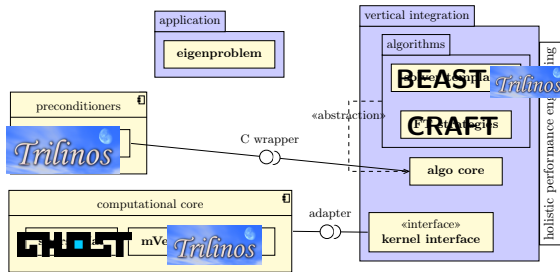
- facilitate algorithm development using **CHOLT**
- holistic performance engineering
- portability and interoperability



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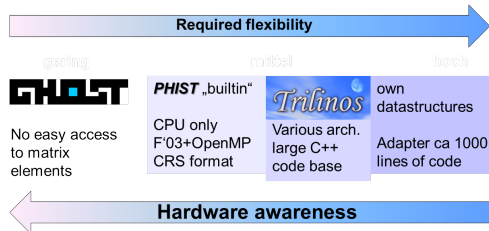
- facilitate algorithm development using **GHOST**
- holistic performance engineering
- portability and interoperability



## Useful Abstraction: Kernel Interface

Choose from several 'backends' at compile time, to

- easily use **PHIST** in existing applications
- perform the same run with different kernel libraries
- compare numerical accuracy and performance
- exploit unique features of a kernel library (e.g. preconditioners)



## What's new in PHIST ?

### New features

- allow general preconditioners in Jacobi-Davidson solver
- solve generalized EVP (with hpd B):  $\mathbf{Ax} = \lambda \mathbf{Bx}$
- new blocked Krylov solvers BiCGStab and TFQMR
- full GPU and hybrid support with **CHOLT**
- automatically generated Fortran 2003 and C++ bindings for C API
- new kernel libraries: PETSc, Eigen

### New applications

- stability analysis of flows (ongoing, with U. Groningen)
- rational Krylov method for model order reduction (ongoing work @ MPI Magdeburg)
- material science (structure optimization, plans with U. Erlangen and DLR material physics)



## Outlook

- integrate **GHELT** kernels into Trilinos/Kokkos
- **PHIST** to enter the xSDK (<https://xsdk.info/>)
- implementation of kernels with data dependencies using RACE (Gauß-Seidel, Kaczmarz and (multi-level) ILU)





## Questions?

### Contact

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The ESSEX II team

